



# Models for the Hop-constrained Steiner Tree Problem

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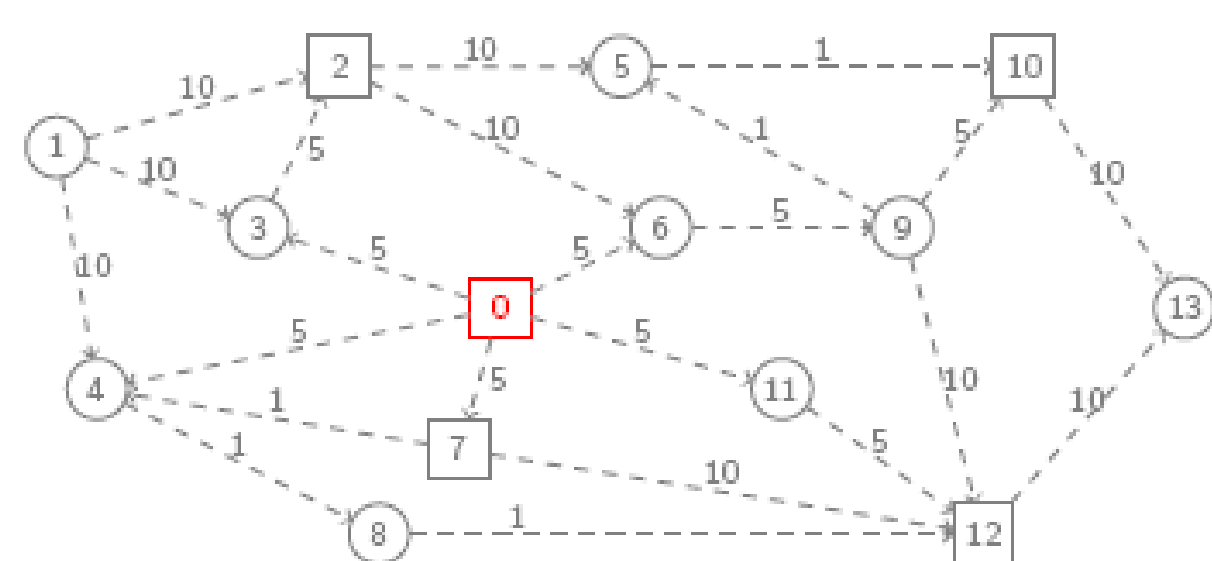
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## The Problem (HSTP)

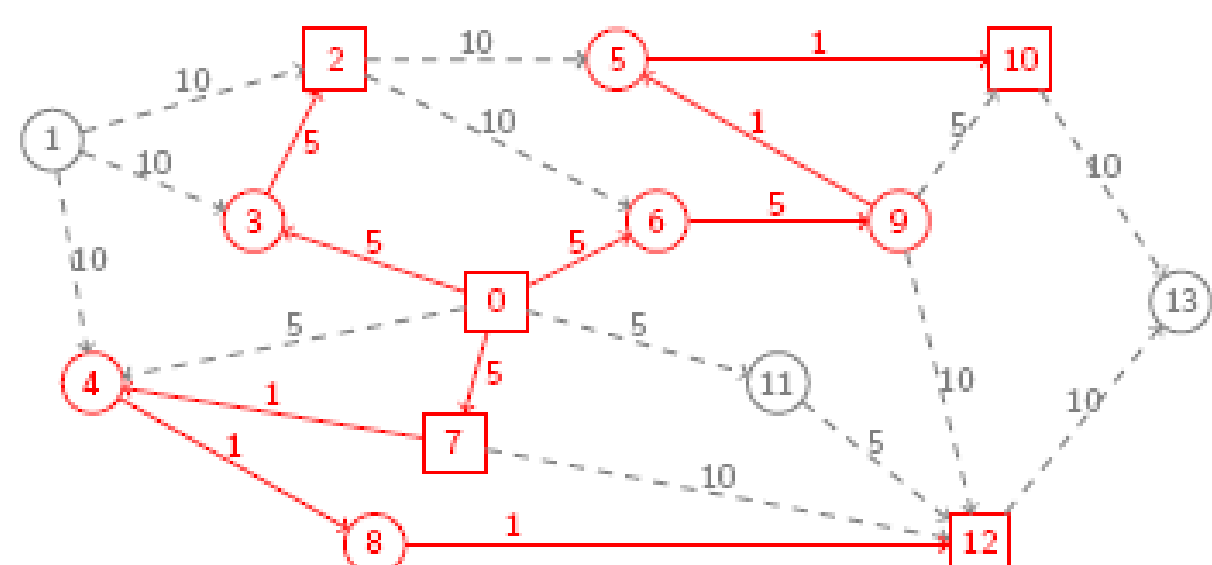
- Given
  - a directed graph  $G = (N, A)$  with:
    - node set,  $N = \{0, 1, \dots, n\}$ ,
    - arc set,  $A = \{(i, j) : i, j \in N\}$  and a function  $c_{ij} > 0, \forall (i, j) \in A$
    - required nodes set,  $R \subseteq N, 0 \in R$
  - Hop limit,  $H \in \mathbb{N}$
- Find an arborescence  $G' = (S, A(S))$ , rooted at 0 with  $S \subseteq N, A(S) \subseteq A$ :
  - $R \subseteq S, |path_{0 \rightarrow r}| \leq H$  arcs,  $\forall r \in R$
  - $C(A(S)) = \sum_{(i,j) \in A(S)} c_{ij}$  is minimum

## Examples

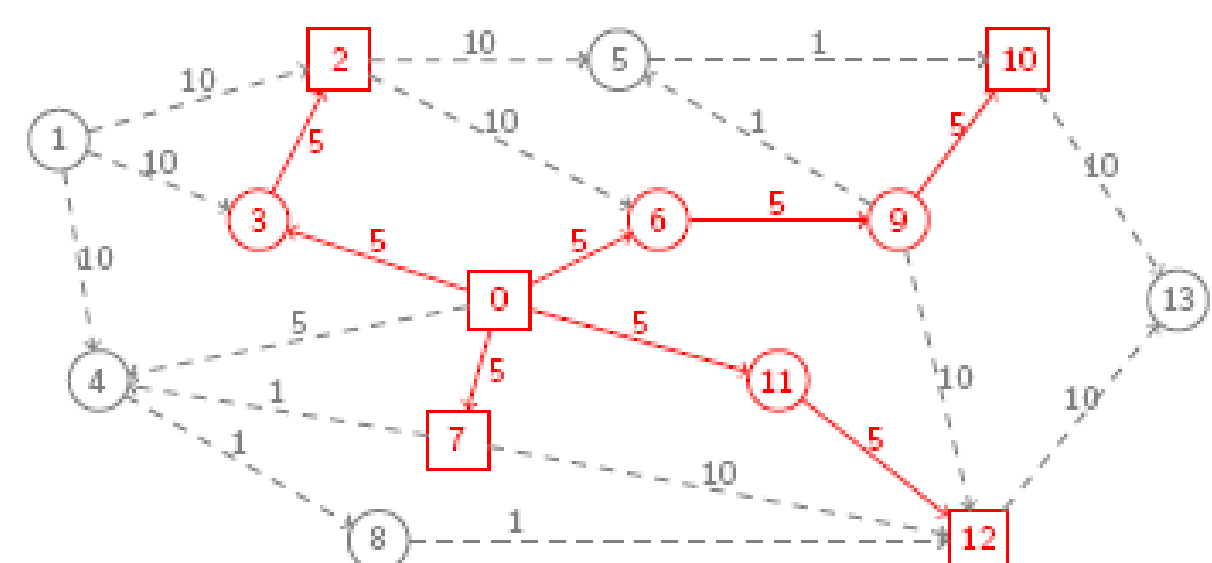
- $H = 2$ : no solution



- $H = 3$ :  $C(A(S)) = 40$



- $H = 4$ :  $C(A(S)) = 35$



## The Node Hop-indexed Model

$$\begin{aligned}
 i \in N \setminus \{0\} : & \quad y_i = 1, \text{ if } i \in S \text{ (0, otherwise)} \\
 (i, j) \in A : & \quad x_{ij} = 1, \text{ if } (i, j) \in A(S) \text{ (0, otherwise)} \\
 i \in N \setminus \{0\}, h \in \{1\} \cup \mathbb{H} : & \quad v_i^h = 1, \text{ if } i \text{ is at distance } h \text{ from the root (0, otherwise)}
 \end{aligned}$$

$$\sum_{(i,j) \in A} x_{ij} = y_j \quad j \in N \setminus \{0\} \quad (1)$$

$$\sum_{h \in \{1\} \cup \mathbb{H}} v_i^h = y_i \quad i \in N \setminus \{0\} \quad (2)$$

$$v_j^1 = x_{0j} \quad (0, j) \in A \quad (3)$$

$$v_i^{h-1} + x_{ij} \leq v_j^h + 1 \quad (i, j) \in A, i \in N \setminus \{0\}, h \in \mathbb{H} \quad (4)$$

$$v_i^H + x_{ij} \leq 1 \quad (i, j) \in A, i \in N \setminus \{0\} \quad (5)$$

$$y_i = 1 \quad i \in R \setminus \{0\} \quad (6)$$

$$x_{ij} \in \{0, 1\} \quad (i, j) \in A \quad (7)$$

$$y_i \in \{0, 1\} \quad i \in N \setminus \{0\} \quad (8)$$

$$v_i^h \in \{0, 1\} \quad i \in N \setminus \{0\}, h \in \{1\} \cup \mathbb{H} \quad (9)$$

### Result

Model (1) - (9) is **not** a valid formulation for the HSTP since connectivity between the root node and the required nodes is not guaranteed

Strengthening and generalizing constraints (4):

$$v_j^H + \sum_{h \in M} v_i^{h-1} + x_{ij} \leq \sum_{h \in M} v_j^h + y_i \quad i \in N \setminus \{0\}, (i, j) \in A, M \subseteq \mathbb{H} \quad (4^+)$$

New Valid Inequalities (symmetric version of (4)):

$$v_j^h + x_{ij} \leq v_i^{h-1} + 1 \quad i \in N \setminus \{0\}, (i, j) \in A, h \in \mathbb{H} \quad (10)$$

### Result

Model (NHB): (1) - (3), (5) - (9), (10) is a valid formulation for the HSTP

Strengthening and generalizing constraints (10):

$$v_j^1 + \sum_{h \in Q} v_j^h + x_{ij} \leq y_j + \sum_{h \in Q} v_i^{h-1} \quad i \in N \setminus \{0\}, (i, j) \in A, Q \subseteq \mathbb{H} \quad (10^+)$$

Model (NHB<sup>+</sup>): (1) - (3), (5) - (9), (10<sup>+</sup>)

## The Arc Hop-indexed Model

$$\begin{aligned}
 i \in N \setminus \{0\} : & \quad y_i = 1, \text{ if } i \in S \text{ (0, otherwise)} \\
 (i, j) \in A : & \quad x_{ij} = 1, \text{ if } (i, j) \in A(S) \text{ (0, otherwise)} \\
 (i, j) \in A, h \in \{1\} \cup \mathbb{H} : & \quad z_{ij}^h = 1, \text{ if } (i, j) \text{ is in position } h \text{ in the } path_{0 \rightarrow j} \text{ (0, otherwise)}
 \end{aligned}$$

$$\sum_{(i,j) \in A} x_{ij} = y_j \quad j \in N \setminus \{0\} \quad (1)$$

$$(AH) \text{ model } \quad z_{0j}^1 = x_{0j} \quad j : (0, j) \in A \quad (11)$$

$$\sum_{h \in \mathbb{H}} z_{ij}^h = x_{ij} \quad i \in N \setminus \{0\}, (i, j) \in A \quad (12)$$

$$\sum_{(k,i) \in A, k \neq 0} z_{ki}^{h-1} \geq z_{ij}^h \quad i \in N \setminus \{0\}, (i, j) \in A, h \in \mathbb{H}, h \geq 3 \quad (13)$$

$$z_{0i}^1 \geq z_{ij}^2 \quad i, j \in N \setminus \{0\} : (0, i), (i, j) \in A \quad (14)$$

$$y_i = 1 \quad i \in R \setminus \{0\} \quad (6)$$

$$x_{ij} \in \{0, 1\} \quad (i, j) \in A \quad (7)$$

$$y_i \in \{0, 1\} \quad i \in N \setminus \{0\} \quad (8)$$

$$z_{ij}^h \in \{0, 1\} \quad i \in N \setminus \{0\}, (i, j) \in A, h \in \mathbb{H} \quad (15)$$

$$z_{0j}^1 \in \{0, 1\} \quad (0, j) \in A \quad (16)$$

### Result

Model (AH) dominates (NHB<sup>+</sup>) in terms of the Linear Program Relaxation

Strengthening constraints (13) by removing  $z_{ji}^{h-1}$  from the summation:

$$\sum_{(k,i) \in A, k \neq 0, j} z_{ki}^{h-1} \geq z_{ij}^h \quad i \in N \setminus \{0\}, (i, j) \in A, h \in \mathbb{H}, h \geq 3 \quad (13^+)$$

Model (AH<sup>+</sup>): (1), (6) - (8), (11), (12), (13<sup>+</sup>), (14), (15), (16)

## Results

- Instances:** Symmetric complete graphs with 20, 40 and 80 nodes, 20%, 40% and 60% required nodes and  $H = 2, 3, 4, 5$
- Tested models:** (NHB<sup>+</sup>), (AH) and (AH<sup>+</sup>)
- Linear Programming gaps:**
  - increase with increasing  $H$ , decreasing number of required nodes
  - the weaker arc model (AH) reduces the node model (NHB<sup>+</sup>) LP gaps in 0% - 17%
  - the stronger arc model (AH<sup>+</sup>) reduces the arc model (AH) LP gaps in 0% - 12%
- CPU times:**
  - LP relaxation: 0 - 40 sec.; Integral models: arc models less than 30 sec., (NHB<sup>+</sup>) spent more time (some  $\approx$  1 hour)

## References

- L. Gouveia, *Using hop-indexed models for constrained spanning and Steiner tree models*, 1999, Telecommunications network planning, Springer
- L. Gouveia, M. Leitner and M. ruthmair, *Layered graph approaches for combinatorial optimization problems*, 2019, Comp. & OR
- M. Sinnl and I. Ljubic, *A node-based layered graph approach for the STP with revenues, budget and hop-constraints*, 2016, Math. Program. Comp.